



# Efficient Implicit SDF and Color Reconstruction via Shared Feature Field



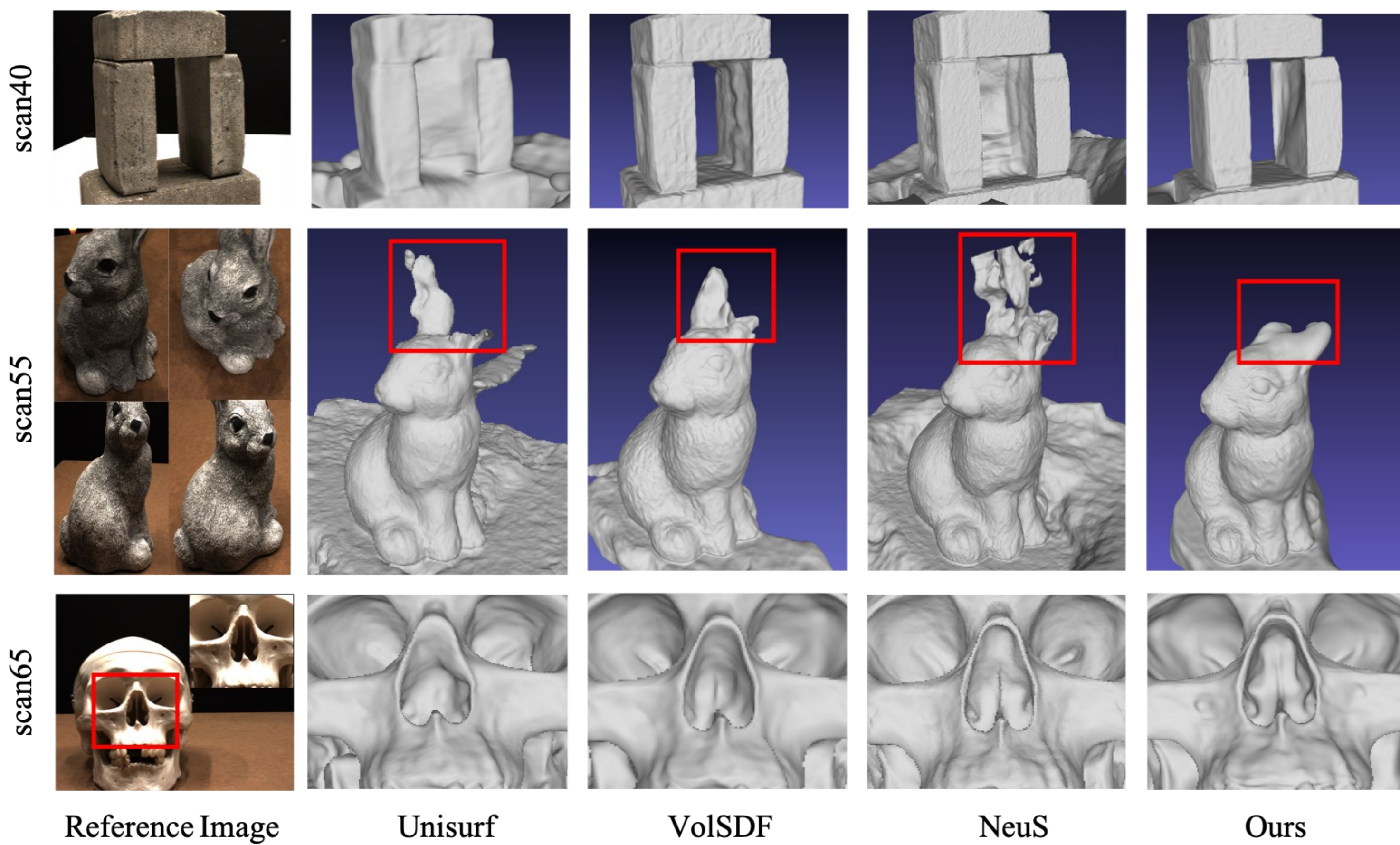
Shuangkang Fang<sup>1\*</sup>, Dacheng Qi<sup>1\*</sup>, Weixin Xu<sup>2</sup>, Yufeng Wang<sup>1</sup>,

Zehao Zhang<sup>1</sup>, Xiaorong Zhang<sup>1</sup>, Huayu Zhang<sup>1</sup>, Zeqi Shao<sup>1</sup>, Wenrui Ding<sup>1</sup>

<sup>1</sup>Beihang University & <sup>2</sup>Megvii Inc. \* Indicates equal contribution

## Motivation

Scenes with **complex topologies** or **textureless regions** lack **pixel-wise masks** for supervision, making full scene recovery challenging. Bridging this gap is essential for robust scene understanding.



\* Comparison with standard methods using approximately half of the training images from the DTU MVS dataset.

## Our Contributions:

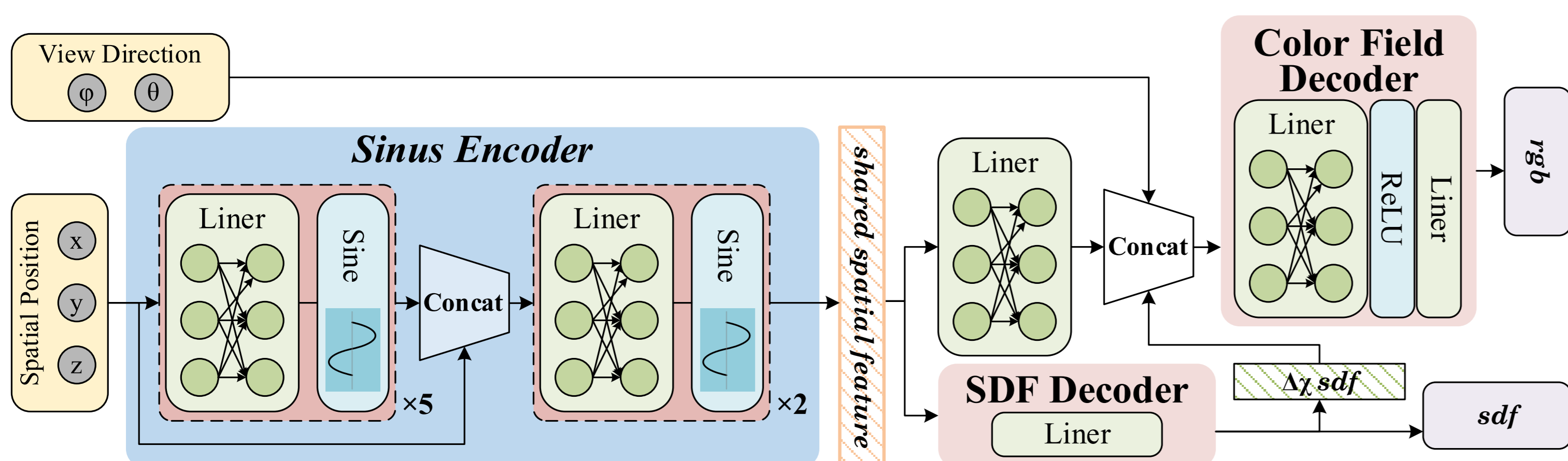
- We propose an end-to-end network tailored for **textureless scenes** and **sparse input** reconstruction.
- We design a **Sinus-ReLU activation function** to reduce artifacts and improve synthesis quality.

## Shared Feature Field

Our SFF combines the multiple MLPs paradigm with an **Encoder-Decoder paradigm** and a **mixed Sinus-ReLU activation function paradigm**.

### Encoder-Decoder paradigm

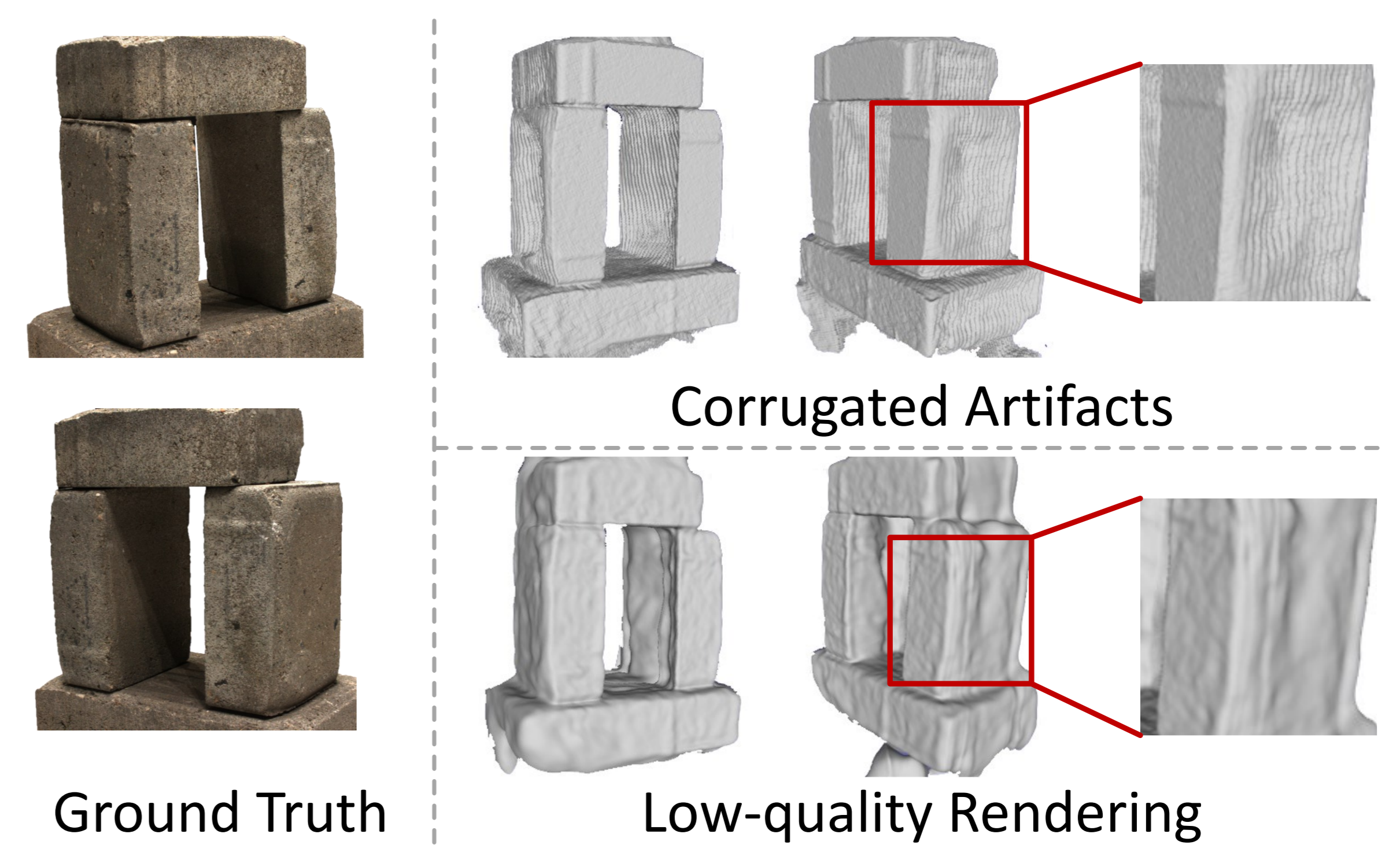
Traditional methods use separate MLPs for encoding and decoding, causing positional ambiguity and poor geometric consistency. We propose a **weight-shared encoder-decoder**, generating **shared spatial features** in a single pass to improve regularization and accuracy.



Compared to the common paradigm, where the color field is conditioned on  $[x, v, \nabla_x sdf, F_{sdf}]$ , we allow the SDF and color field to share the **same feature  $F$**  from the encoder, while obtaining the spatial position through an additional forward pass.

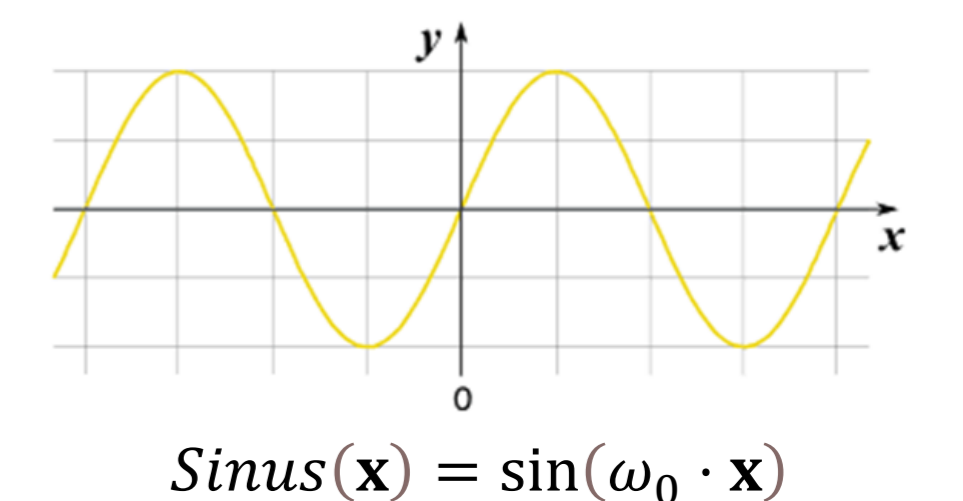
## Mixed Sinus-ReLU Activation Function Paradigm

We observe that high-frequency positional encoding of spatial positions introduces **corrugated artifacts** on the mesh, while low-frequency positional encoding leads to **lower-quality novel view rendering**.



To improve view quality and reduce artifacts, we replace positional encoding with a **mixed Sinus-ReLU activation**, using sinus for the encoder and ReLU for the decoders.

In the Sinus activation function,  $\omega_0$  is a **trainable parameter** initialized to **3**. Network weights are initialized using a **uniform distribution**:

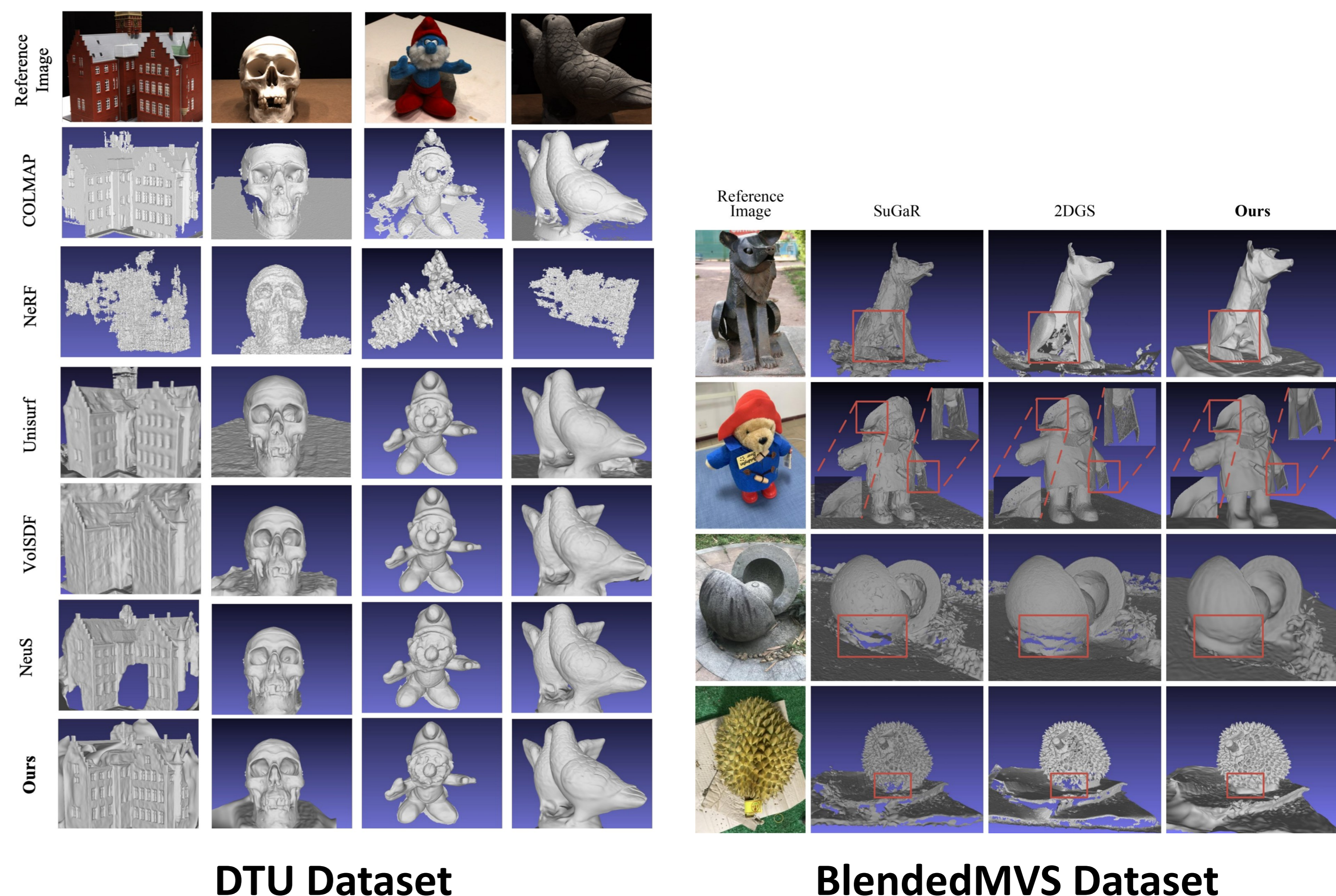


$$W \sim U\left(-\sqrt{\frac{6}{ic}}/\omega_0, \sqrt{\frac{6}{ic}}/\omega_0\right),$$

except for the first layer, which is initialized as :

$$W \sim U\left(-\sqrt{\frac{1}{ic}}, \sqrt{\frac{1}{ic}}\right)$$

## Experiments



DTU Dataset

BlendedMVS Dataset